

[illegible]

--	--	--	--	--	--	--

```
public class Main extends OpMode {
```

//

@Override

```
public void init() {
```

} ...

}

//

DcMotor motor;

[illegible]

--	--	--	--	--	--	--	--

init

```
//motor = hardwareMap.get(DcMotor.class, "motor");  
motor = hardwareMap.get(DcMotor.class, "motor");
```



```
loop  
Power[-1][1]
```

```
//motor.setPower(0.1(1));  
motor.setPower(0.1);
```



```
package org.firstinspires.ftc.teamcode;  
  
import com.qualcomm.robotcore.eventloop.opmode.OpMode;  
import com.qualcomm.robotcore.eventloop.opmode.TeleOp;  
import com.qualcomm.robotcore.hardware.DcMotor;  
  
@TeleOp(name = "Main OpMode", group = "Main")  
public class Main extends OpMode {  
  
    //DcMotor motor;  
    DcMotor motor;  
  
    /*  
    * INIT  
    */  
    @Override  
    public void init() {  
        motor = hardwareMap.get(DcMotor.class, "motor");  
        telemetry.addData("Status", "Initialized");  
    }  
  
    /*  
    * INIT PLAY  
    */
```

```

*/
@Override
public void init_loop() {
}

/*
 * ████████████████████
 */
@Override
public void start() {
    telemetry.addData("Status", "Started");
}

/*
 * Enable██████████
 * while (opModelsActive()) ████
 */
@Override
public void loop() {
    motor.setPower(0.1);
}

/*
 * ████████████████████
 */
@Override
public void stop() {
    telemetry.addData("Status", "Stopped");
}
}

```

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